

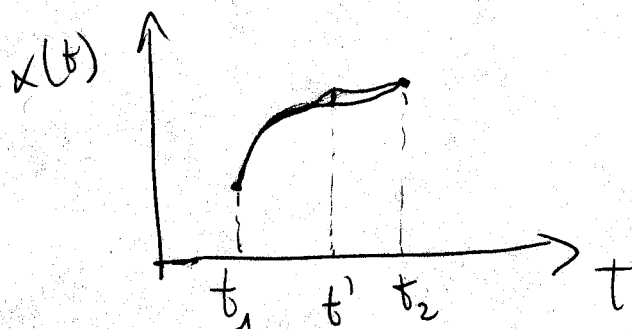
Notes from the discussion of Friday, 2/4/2005

the functional derivative ~~is~~ is defined as

$$\frac{\delta S[x(t)]}{\delta x(t')} = \lim_{\epsilon \rightarrow 0} \left[ S[x(t) + \epsilon \delta(t-t')] - S[x(t)] \right]$$

for a functional  $S[x(t)]$ .

The physical meaning of the variation  $\epsilon \delta(t-t')$  is that the trajectory  $x(t)$  is slightly perturbed only at one (arbitrary) time  $t'$  between  $t_1$  and  $t_2$ .



The previous definition can be rewritten by replacing

$$\delta(t-t') = \lim_{\Delta t \rightarrow 0} \frac{1}{\Delta t} \delta_{ij}$$

so that

$$\frac{\delta S_N}{\delta x(t)} = \lim_{\Delta t \rightarrow 0} \frac{\partial S_N}{\partial x_i}$$

In other words, the trajectory has been discretized,

so that

$$S_N = \Delta t \sum_{i=0}^{N-1} \left[ \frac{m}{2} \left( \frac{x_{i+1} - x_i}{\Delta t} \right)^2 - V(x_i) \right]$$

For a system whose classical Lagrangian does not depend on time explicitly nor has terms of the type  $\dot{x}^2$ .

Now

$$\frac{\partial S_N}{\partial x_i} = \Delta t \left[ m \left( \frac{x_i - x_{i-1}}{\Delta t} \right) - \frac{x_{i+1} - x_i}{\Delta t} - \frac{\partial V}{\partial x_i} \right]$$

$$= \frac{2m(x_i - x_{i+1})}{\Delta t} - \frac{\partial V}{\partial x_i} = \frac{\partial L}{\partial \dot{x}_i} + \frac{\partial L}{\partial x_i}$$

in the limit of  $\Delta t \rightarrow 0$

this can be useful, since the first variation of the action

$$\delta S[x(t)] = \lim_{\Delta t \rightarrow 0} \delta S_N = \lim_{\Delta t \rightarrow 0} \sum_{i=0}^{N-1} \frac{\partial S_N}{\partial x_i} \delta x_i$$

is, in the limit  $\Delta t \rightarrow 0$

$$\int_{t_1}^{t_2} dt \left( \frac{\partial L}{\partial \dot{x}_i} \delta \dot{x}_i + \frac{\partial L}{\partial x_i} \delta x_i \right)$$

In general, it turns out that

$$\delta^m S = \int_{t_1}^{t_2} dt \left[ \frac{\partial L}{\partial \dot{x}^m} \delta \dot{x}^m + \frac{\partial L}{\partial x^m} \delta x^m + \dots + \frac{\partial L}{\partial x^n} \delta x^n \right]$$

This comes in hand everytime we want to expand the action about one of its stationary points:

$$S[\bar{x}(t) + \delta x(t)] = S[\bar{x}(t)] + \delta S + \frac{1}{2} \delta^2 S + \dots$$



Path integral formulation for the one-dimensional simple harmonic oscillator: (From Zuber-Itzykson, QFT, McGraw-Hill 1980)

We first compute the increment in action of the oscillator in going from  $(q_1, t)$  to  $(q_2, t+\Delta t)$ .  
 On this infinitesimal time-interval  $(t, t+\Delta t)$  we approximate an arbitrary path by a linear one in such a way that the increment in action is —

$$\Delta I(2,1) = \frac{1}{2} m \left[ \frac{(q_2 - q_1)^2}{\Delta t} - \omega^2 \Delta t \frac{q_2^2 + q_1 q_2 + q_1^2}{3} \right]$$

Set  $t = t_f - t_i$

So, now —

$$\langle f | i \rangle = \lim_{n \rightarrow \infty} \int \prod_{p=1}^{n-1} dq_p \left( \frac{nm e^{-i\omega t/2}}{2\omega t} \right)^{n/2} \exp \left\{ \frac{im}{2t} \left[ \sum_{p=1}^n (q_p - q_{p-1})^2 - \frac{\omega^2 t}{3n} (q_p^2 + q_p q_{p-1} + q_{p-1}^2) \right] \right\}$$

The argument of the exponential function can be cast in the form of a positive-definite form:

$$\exp \left( \frac{im}{2} [q^T M q] \right)$$

where  $q = (q_0 = q_i, q_1, \dots, q_n = q_f)$  and  $M$  is a  $n \times n$  matrix such that —

$$M_{00} = M_{nn} = \frac{n}{t} - \frac{\omega^2}{3n} t$$

$$M_{kk} = 2 \left( \frac{n}{t} - \frac{\omega^2 t}{3n} \right)$$

$$M_{k, k+1} = M_{k-1, k} = - \left( \frac{n}{t} + \frac{\omega^2 t}{6n} \right) \quad 1 \leq k \leq n-1$$

all other matrix elements being zero.

If  $N$  is the matrix obtained from  $M$  by deleting the rows and columns with indices 0 and  $n$ , then we can write -

$$q^T M q = M_{00} (q_0^2 + q_n^2) + 2 M_{01} (q_0 q_1 + q_{n-1} q_n) + \sum_{j=2}^{n-1} q_j N_{jk} q_k$$

So the  $N$ -integral is evaluated as -

$$\int d^{n-1} q e^{\frac{i m}{2} q^T N q} = \left( \frac{2\pi}{m} e^{i\pi/2} \right)^{\frac{n-1}{2}} (\det N)^{-1/2}$$

Since the problem has translational invariance, that takes care of the linear terms in the exponential, so we are left with -

$$\langle f|i \rangle = \lim_{\hbar \rightarrow \infty} \left( \frac{n m e^{-i\pi/2}}{2\pi \hbar t} \right)^{n/2} \left( \frac{2\pi \hbar e^{i\pi/2}}{m} \right)^{(n-1)/2} (\det N)^{-1/2} \times \exp \left\{ \frac{i m}{2} [M_0 (q_0^2 + q_n^2) - M_{01}^2 (N_{11}^{-1} q_0^2 + N_{n-1, n-1}^{-1} q_n^2 + 2 N_{1, n-1}^{-1} q_0 q_n)] \right\}$$

Let us now define

$$a = \frac{1}{2} \left( \frac{1 + \omega^2 t^2 / 6n^2}{1 - \omega^2 t^2 / 3n^2} \right)$$

Now,

$$\det N = 2^{n-1} \left( \frac{n}{t} - \frac{\omega^2 t}{3n} \right)^{n-1} \det_{n-1} \begin{vmatrix} 1 & -a & 0 & \dots \\ -a & 1 & -a & \dots \\ 0 & -a & 1 & -a \\ \vdots & \vdots & \vdots & \vdots \end{vmatrix}$$

Let us call the  $(n-1) \times (n-1)$  determinant  $I_{n-1}(a)$ . Then for fixed 'a' we have the recursion relation —

$$I_p(a) = I_{p-1}(a) - a^2 I_{p-2}(a) \quad I_0(a) = I_1(a) = 1$$

or, in matrix form —

$$\begin{pmatrix} I_p(a) \\ I_{p-1}(a) \end{pmatrix} = \begin{pmatrix} 1 & -a^2 \\ 1 & 0 \end{pmatrix}^{p-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

After diagonalization of the  $2 \times 2$  matrix the solution is obtained as —

$$I_{n-1}(a) = \frac{\lambda_+^n(a) - \lambda_-^n(a)}{\lambda_+(a) - \lambda_-(a)} \quad \lambda_{\pm}(a) = \frac{1 \pm i\sqrt{4a^2-1}}{2} \underset{n \rightarrow \infty}{\sim} \frac{1}{2} e^{\pm i \cot \frac{\omega t}{n}}$$

iso for large n ,

$$I_{n-1}(a) \sim \frac{n}{2^{n-1}} \frac{\sin \omega t}{\omega t}$$

Thus,

$$\langle f|i \rangle = \left( \frac{m\omega e^{-i\pi/2}}{2\pi \sin \omega t} \right)^{1/2} \lim_{n \rightarrow \infty} \exp \left\{ \frac{im}{2} \left[ (q_i^2 + q_f^2) (M_{00} - M_{01}^2 N_{11}^{-1}) - 2q_i q_f M_{01}^2 N_{1, n-1}^{-1} \right] \right\}$$

We assume  $0 < \omega t < \pi$  and then evaluate —

$$N_{11}^{-1} = \frac{t}{2n(1 - \omega^2 t^2 / 3n^2)} \frac{I_{n-2}(a)}{I_{n-1}(a)} \sim \frac{t}{n} \left( 1 - \frac{\omega t \cot \omega t}{n} \right) + O\left(\frac{1}{n^3}\right)$$

similarly,  $N_{1, n-1}^{-1} \sim \frac{\omega t^2}{n^2 \sin \omega t} + O\left(\frac{1}{n^3}\right)$

So finally —

$$\langle f|i \rangle = \left( \frac{m\omega e^{-i\pi/2}}{2\pi \sin \omega t} \right)^{1/2} \exp \left\{ \frac{im\omega}{2} \left[ (q_f^2 + q_i^2) \cot \omega t - \frac{2q_i q_f}{4 \sin \omega t} \right] \right\}$$

Now, how to get to the energy spectrum?

In general, the propagator (or Green's function)

$$K(x', x, t) = \sum_j \langle x' | \psi_j \rangle \langle \psi_j | x \rangle e^{-\frac{iE_j t}{\hbar}}$$

assuming that the system has a discrete spectrum of eigenenergies.

Now

$$K(x, x, t) = \sum_j |\langle x | \psi_j \rangle|^2 e^{-\frac{iE_j t}{\hbar}}$$

is the propagator for a periodic orbit, and

$$\begin{aligned} G(t) &= \int dx K(x, x, t) = \int dx \sum_j |\langle x | \psi_j \rangle|^2 e^{-\frac{iE_j t}{\hbar}} \\ &= \sum_j e^{-\frac{iE_j t}{\hbar}} \int dx |\langle \psi_j | x \rangle|^2 = \sum_j e^{-\frac{iE_j t}{\hbar}} \end{aligned}$$

~~that is~~ which is nothing but the trace of the time-evolution operator  $K(x', x, t)$

~~Let's~~ now take a Laplace-Fourier transform of  $G(t)$ :

$$\hat{G}(\mathcal{E}) = -i \int_0^{\infty} dt G(t) e^{\frac{i\mathcal{E}t}{\hbar}} =$$

$$= -i \int_0^{\infty} dt \sum_j e^{\frac{i(\mathcal{E} - \mathcal{E}_j)t}{\hbar}} \quad \text{which does not}$$

exist, but if we ~~add~~ add a small imaginary part to the energy, i.e.  $\mathcal{E} \rightarrow \mathcal{E} + i\sigma$ , then

$$\hat{G}(\mathcal{E}) = \lim_{\sigma \rightarrow 0} (-i) \int_0^{\infty} dt \sum_j e^{\frac{i(\mathcal{E} - \mathcal{E}_j)t}{\hbar} - \frac{\sigma t}{\hbar}} =$$

$$= \lim_{\sigma \rightarrow 0} \sum_j \frac{\hbar}{\mathcal{E} - \mathcal{E}_j - i\sigma} = \sum_j \frac{\hbar}{\mathcal{E} - \mathcal{E}_j} \quad \left[ \text{cf. Sakurai} \right]$$

So that, given the propagator, the recipe is to

study the analytical properties (i.e. to find the poles)

of the function  $\hat{G}(\mathcal{E}) = \int_0^{\infty} (-i) dt e^{\frac{i\mathcal{E}t}{\hbar}} \int dx K(x, x, t)$